Computer-Aided Design, Analysis and Load Rating of Precast-Prestressed Spliced Girder Bridges

Richard Brice, PE Software Applications Engineer

Lynn Peterson Secretary of Transportation

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Outline

- LRFD Requirements for Spliced Girder Bridges
- Overview of Spliced Girder Analysis
- Computer Aided Design, Analysis, and Load Rating

Design, Analysis, and Rating of Spliced Girder Bridges

- Basic requirements of conventional precastprestressed girder bridges
	- Service stress limitations, ultimate strength requirements, etc.
- LRFD 5.14.1.3 Spliced Precast Girders
	- Additional requirements for contract documents
	- Additional service stress limitations
	- Additional analysis requirements

LRFD Requirement for Time-Step Analysis

LRFD 5.9.5.4.1

For segmental construction and **post-tensioned spliced precast girders, other than during preliminary design, prestress losses shall be determined by the time-step method**... **including consideration of the time-dependent construction stages** and schedule shown in the contract documents.

For components with combined pretensioning and post-tensioning, and where post-tensioning is applied in more that one stage, **the effects of subsequent prestressing on the creep loss of previous prestressing shall be considered.**

Introduction to Time-Step Analysis

- Models design life through discrete time intervals
- Uses fundamental principles of engineering mechanics
- Accounts for time-dependent material properties and responses $(f'_c, \psi, \varepsilon_{shrinkage}, \textit{relaxation})$
- Step-wise pseudo-linear solution to a nonlinear problem
- Structural response at the end of any interval is the summation of the responses of all the preceding intervals

Challenge of Time-Step Analysis

- Sheer quantity of computations that must be performed
	- Deformations are computed at many locations
	- Deformations are computed in every piece of the spliced girder
	- Deformations are computed for the design life of the structure
	- Transformed section properties change with time and location
		- Non-prismatic segments (haunches, varying tendon locations)
		- E_c and thus the modular ratios vary with time
	- Loading conditions change with time
		- Staged application of superimposed loads
		- Multi-staged post-tensioning
	- Statical structural system changes with time
		- Composite closure joints
		- Composite deck
		- Temporary support removal

Composition of Spliced Girders

- Precast concrete segments
- CIP concrete closure joints and deck
- Prestressing Strands and Tendons
- Non-prestressed reinforcement

Time Variation of Material Properties

- Three distinct materials
- Concrete
	- Strength (f_c^{\prime}) and stiffness (E_c) vary with time
	- Creep rate varies with time and time of loading
	- Shrinkage rate varies with time
- Prestressing steel
	- Relaxation rate varies with time and loading
- Non-prestressed Reinforcement
	- Constant with time. Obeys Hooke's Law

- Modeled as a sequence of discrete intervals
	- Begins when segments are constructed
	- Ends at conclusion of design life
- Interval duration is based on changes in loading and the statical structural system
- Intervals are sub-divided to capture time- dependent material responses immediately following a change in forces

Typical Timeline

3. Post-tensioning and removal of temporary supports

Incremental Deformations

- Time-step analysis is simply computing incremental deformations during each interval
- Axial strain and curvature
	- Computed for every part of the girder
	- Caused by
		- externally applied loads
		- change in statical structural system
		- creep and shrinkage of concrete
		- relaxation of prestressing strands and tendons

Computing Incremental Deformations

$$
\Delta\varepsilon_c(i_e, i_b) = \frac{\Delta P_c(i_m)}{A_c E_c(i_m)} [1 + \psi(i_e, i_m)] + \left\{ \sum_{j=1}^{i-1} \frac{\Delta P_c(j_m)}{A_c E_c(j_m)} [\psi(i_e, j_m) - \psi(i_b, j_m)] + \Delta\varepsilon_{sh}(i_e, i_b) \right\}
$$

\n
$$
\Delta\varphi_c(i_e, i_b) = \frac{\Delta M_c(j_m)}{I_c E_c(j_m)} [1 + \psi(i_e, i_m)] + \left\{ \sum_{j=1}^{i-1} \frac{\Delta M_c(j_m)}{I_c E_c(j_m)} [\psi(i_e, j_m) - \psi(i_e, j_m)] \right\}
$$

\n
$$
\Delta\varepsilon_{ps}(i_e, i_b) = \frac{\Delta P_{ps}(i_m)}{A_{ps}E_{ps}} + \left\{ -\frac{\Delta f_r(i_e, i_b)}{E_{ps}} \right\}
$$

\n
$$
\Delta\varepsilon_{ns}(i_e, i_b) = \frac{\Delta P_{ns}(i_m)}{A_{ns}E_{ns}} \Delta P_k = \left[\frac{\Delta P}{A_{tr}E_{tr}} + \frac{\Delta M(Y_{tr} - Y_k)}{I_{tr}E_{tr}} \right] A_k E_k, \Delta M_k = \Delta M \frac{I_k E_k}{I_{tr}E_{tr}} \sum_{i} \sum_{i} \sum_{j} \sum_{j} \sum_{j} \sum_{j} \sum_{j} \sum_{k=1} \overline{P}_{k} = -E_k A_k \varepsilon_k, \overline{M}_k = -E_k I_k \varphi_k
$$

\n
$$
\overline{P} = \sum_{k=1}^{n} \overline{P}_{k}, \overline{M} = \sum_{k=1}^{n} (\overline{M}_k + \overline{P}_k(Y_{tr} - Y_k))
$$

\n
$$
\overline{\varepsilon} = \frac{\overline{P}}{E_{tr}A_{tr}}, \overline{\varphi} = \frac{\overline{M}}{E_{tr}I_{tr}}
$$

Time-Step Analysis By Example

- Simple span reinforced concrete beam
- Self-weight loading

Time Variation of Creep Coefficient

Time Variation of Shrinkage Strain

Time Step 1 – Analyze Loading Condition

- Moment due to self-weight (external force)
- Use transformed section analysis

– Neglect bending stiffness of reinforcement

Time Step 1 – Incremental Deformations

• Incremental forces on the various parts of the cross section are determined by a transformed section analysis

$$
-\Delta P_{c1} = P_c, \Delta M_{c1} = M_c, \Delta P_{r1} = P_r
$$

- Incremental Deformations
	- Computed using modulus at time of loading and net section properties

$$
-\Delta \varepsilon_{c1} = \frac{\Delta P_{c1}}{E_{c1} A_{cn}}, \Delta \varphi_{c1} = \frac{\Delta M_{c1}}{E_{c1} I_{cn}}
$$

$$
-\Delta \varepsilon_{r1} = \frac{\Delta P_{r1}}{E_s A_s}
$$

Time Step 1 – End of Interval

Time Step 2 – Time-Dependent Effects

- Only Time Passes
- Time-dependent response of materials
	- Unrestrained Creep of Concrete

•
$$
\Delta \varepsilon_{cr} = \frac{\Delta P_{c1}}{E_1 A_c} \psi(t_2, t_1)
$$

•
$$
\Delta \varphi_{cr} = \frac{\Delta M_{c1}}{E_1 I_c} \psi(t_2, t_1)
$$

- Unrestrained Shrinkage
	- \bullet $\Delta \varepsilon_{\rm sh}(t_2,t_1)$

Time Step 2 – Initial Strain Analysis

- Reinforcing causing internal restraint
- Compute restrained deformations and internal restraining forces,

Time Step 2 – End of Interval

Time Step 3 – Time-Dependent Effects

- Only Time Passes
- Time-dependent response of materials
	- Unrestrained Creep of Concrete

•
$$
\Delta \varepsilon_{cr} = \frac{\Delta P_{c1}}{E_1 A_c} [\psi(t_3, t_1) - \psi(t_2, t_1)] + \frac{\Delta P_{c2}}{E_2 A_c} \psi(t_3, t_2)
$$

\n• $\Delta \varphi_{cr} = \frac{\Delta M_{c1}}{E_1 I_c} [\psi(t_3, t_1) - \psi(t_2, t_1)] + \frac{\Delta M_{c2}}{E_2 I_c} \psi(t_3, t_2)$

- Unrestrained Shrinkage
	- \bullet $\Delta \varepsilon_{sh}(t_3,t_2)$

Time Step 3 – Incremental Unrestrained Deformations

Unrestrained Axial Creep Strain

Time Step 3 – Initial Strain Analysis

- Reinforcing causing internal restraint
- Compute restrained deformations and internal restraining forces,

Time Step 3 – End of Interval

Time Step *i* – Repeat, Repeat, Repeat

- This procedure is repeated for every cross section and every time interval
- Analysis is more involved for spliced girders
	- Continuity externally restrains free deformations
	- Several concrete types cast at different times
	- Changes in statical structural system
	- Pretensioning and multi-stage post-tensioning
	- Intrinsic and reduced relaxation of prestressed steel
- Computers are great at performing repetitive computations and keeping track of numbers!

Computer Aided Design of Spliced Girders

- NCHRP Report 517 Extending Spans
	- Suggests DOT produced software was a significant contributing factor for wide-spread use of PT Box Girder technology
	- Implies same will be true for adoption of spliced girder technology
	- Notes the lack of a preferred industry standard
	- Recommends owner agencies and industry pursue development of high quality software tools for spliced girder bridges

PGSplice™

- Part of the new WSDOT BridgeLink™ suite of software
- Design, analyze, and load rate continuous precast-prestressed spliced girder bridges
- Modeling
	- Cantilever pier segments
	- Drop-in field segments
	- Temporary erection towers
	- Strong back hangers
	- Multi-stage post-tensioning
- Analysis
	- Non-linear time step analysis
	- AASHTO, ACI 209 and CEB-FIP Model Code
- User interface, modeling, graphing and reporting features are very similar to PGSuper™

Bridge Configurations

4 Span Variable Depth Girder with Cantilever Piers Segments and Drop In Field Segments

Bridge Configurations

3 Span U-Beam with Segments Supported at Permanent Piers and Temporary Erection Towers

Bridge Configurations

End Spans are pretensioned girders - center span three segment spliced girder

Graphical Results

• Visualize Complex Results with Simple Graphical Representations

Detailed Reporting

• Transparent – eliminate frustration with "black boxes"

Case Study

- Two Span Continuous Spliced Girder Bridge
- Presented in PCI State-of-the-Art of Spliced-Girders report

Baseline Comparison

Washington State
Department of Transportation

Comparison including Time-Dependent Effects

Software Availability

- Free download from WSDOT
	- http://www.wsdot.wa.gov/eesc/bridge/software
- Open Source
- BridgeLink™ v1.0
	- PGSuper™ v3.0 (Beta)
	- PGSplice™ v3.0 (Beta)
	- BEToolbox™ v3.0

http://www.wsdot.wa.gov/eesc/bridge/software

