

# Western Bridge Engineers' Seminar



*Images at Depth:  
The Use of Acoustic Imaging  
on Large River Crossings –  
A Case Study*



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# AGENDA

- Background of project
- Review of underwater scanning technology
- Evaluation procedures
- Results and lessons learned



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## Challenge

*How to inspect large river crossings where it is nearly impossible to perform a 100% underwater inspection due to massive size of piers, depth, flow and zero visibility*

## Possible Solution

*Use scanning technology to identify “anomalies” underwater, then have divers inspect only these locations*



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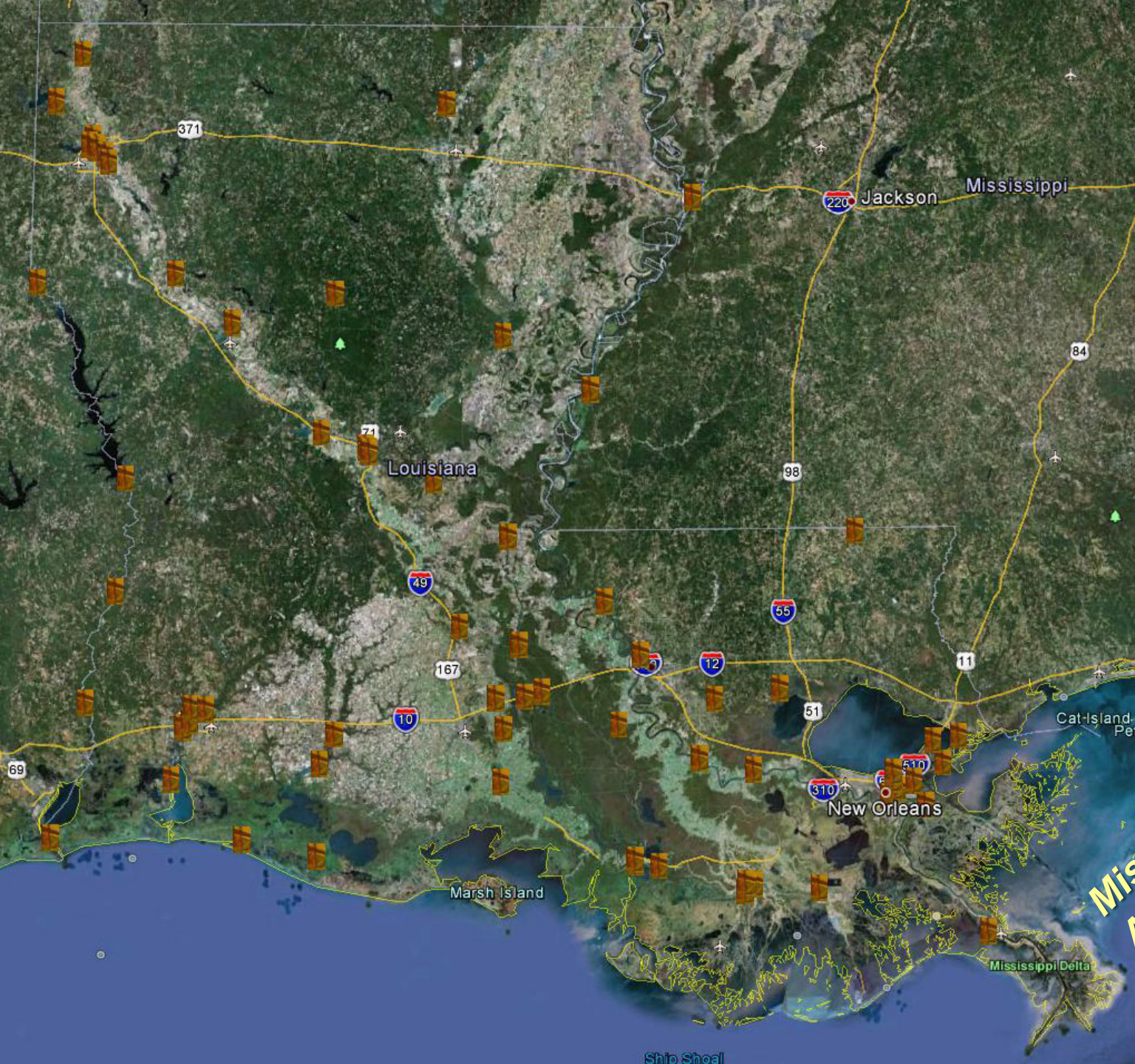






*69 large  
river  
crossings  
located  
across the  
state*

*Mississippi River  
Afchafalaya River  
Red River  
Calcasieu River  
and others*





# Bridge Substructure Types

- *Caisson founded on monolithic piers*
- *Pile-supported spread footings with columns*
- *Drilled shafts*
- *Pile-supported waterline and above water footings*



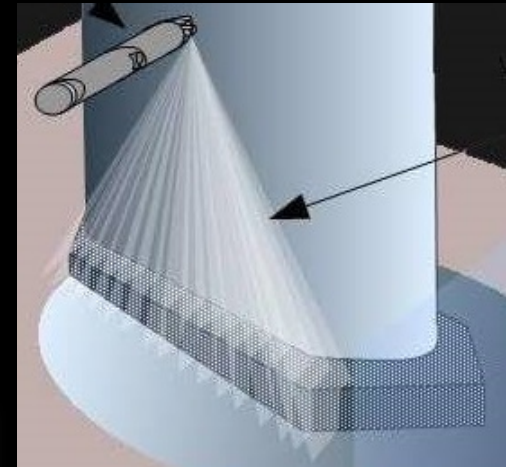
# Currently Available Remote Sensing Technology

## Underwater Acoustic Systems

### *Steered Beam Sonar*

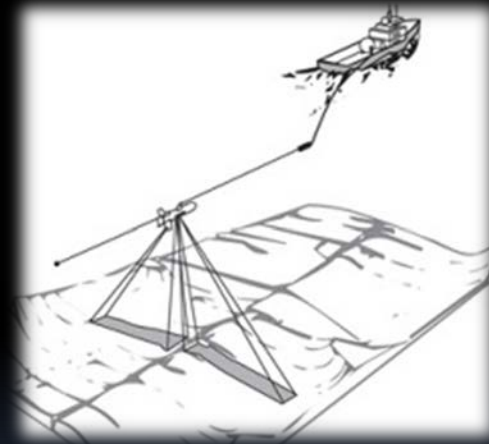
*Optimal for vertical structures*

*Currently also the most cost effective*



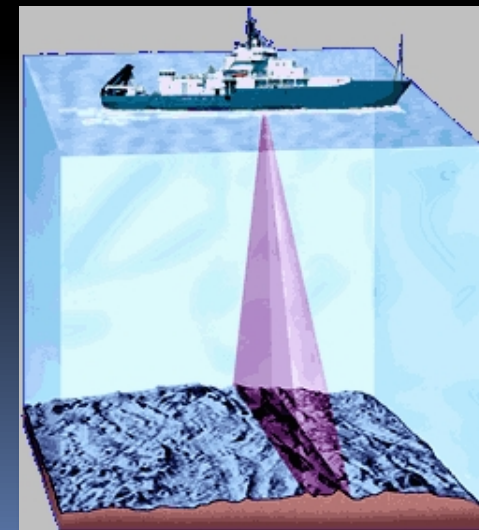
### *Side Scan Sonar*

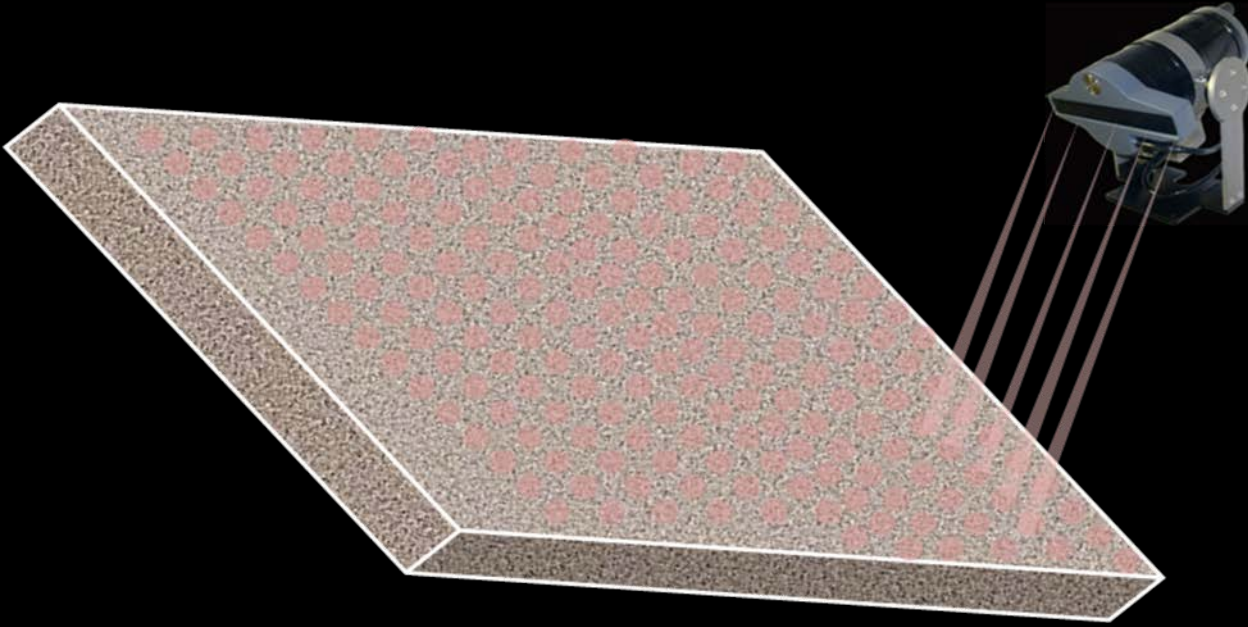
*Not applicable for vertical structures*



### *Multibeam Acoustic Systems*

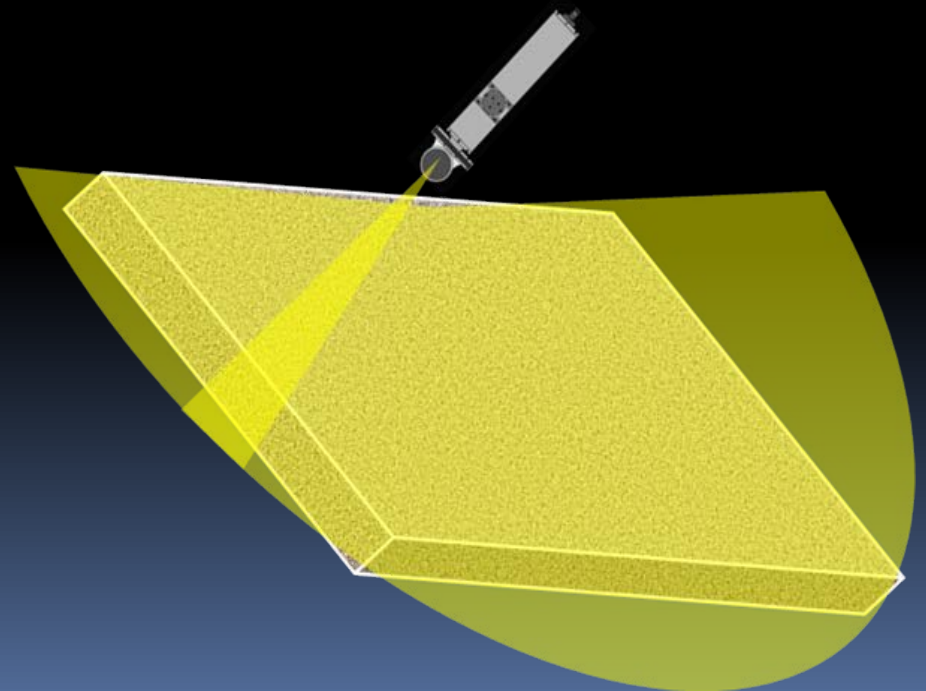
*Can be adapted to vertical structures*



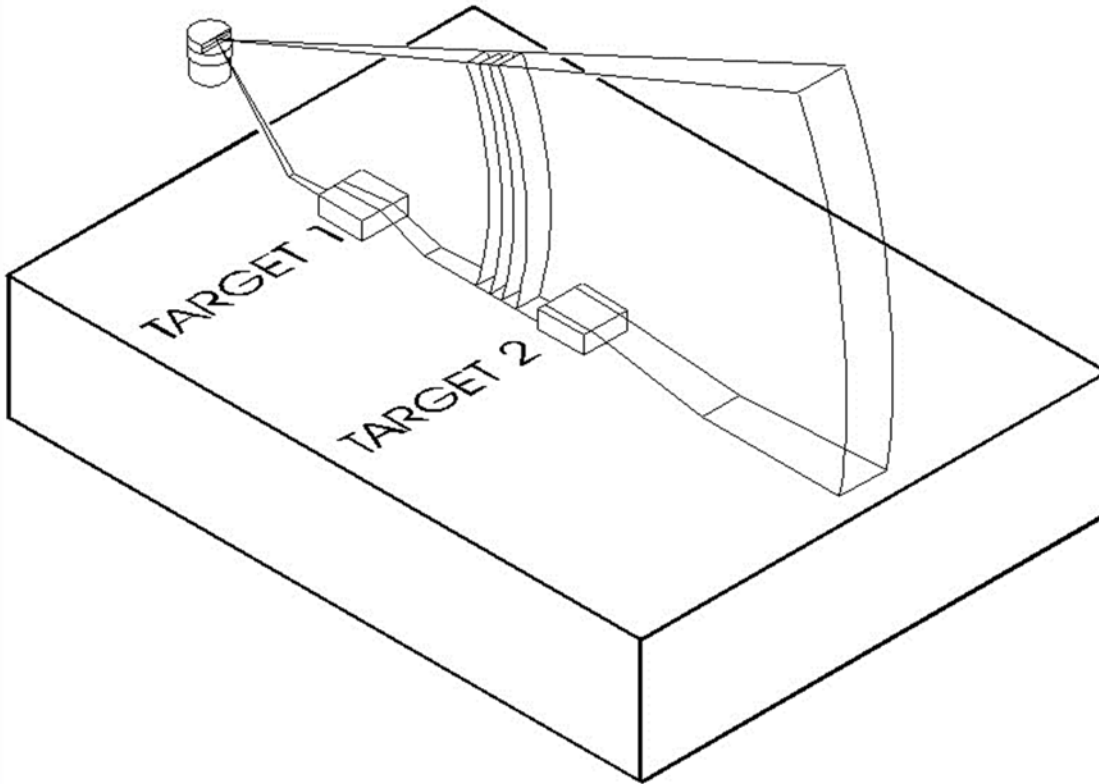


*Multibeam  
record consists of  
multiple, discrete  
points  
corresponding to  
returns mapped  
at each  
transducer*

*Mechanically scanned sonar  
record consists of a continuous  
record of amplitude reflections  
from the transducer to the scan  
range limit providing a seamless  
image translation*



# Mechanically Scanned Sonar Surface Mapping Methodology

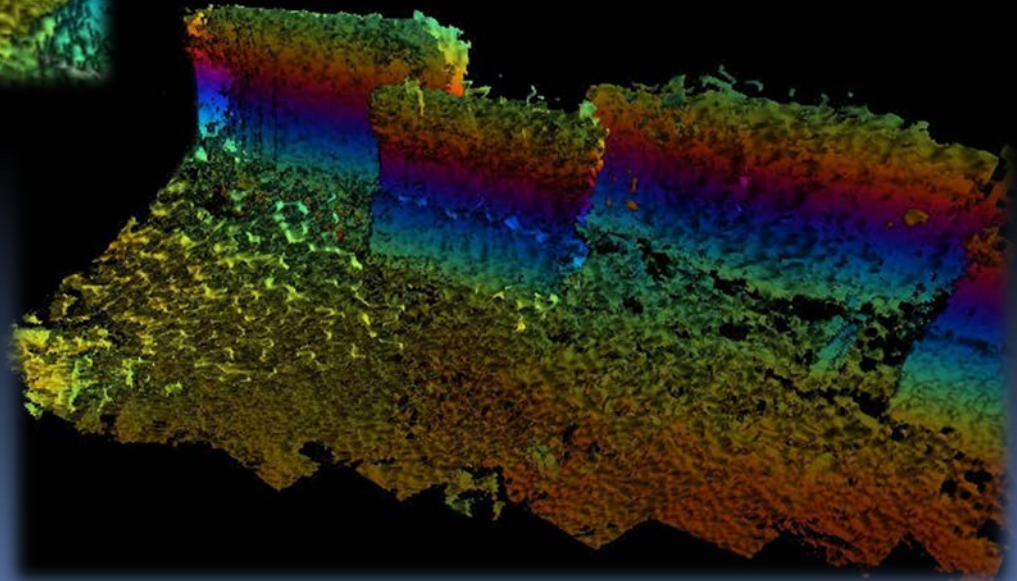
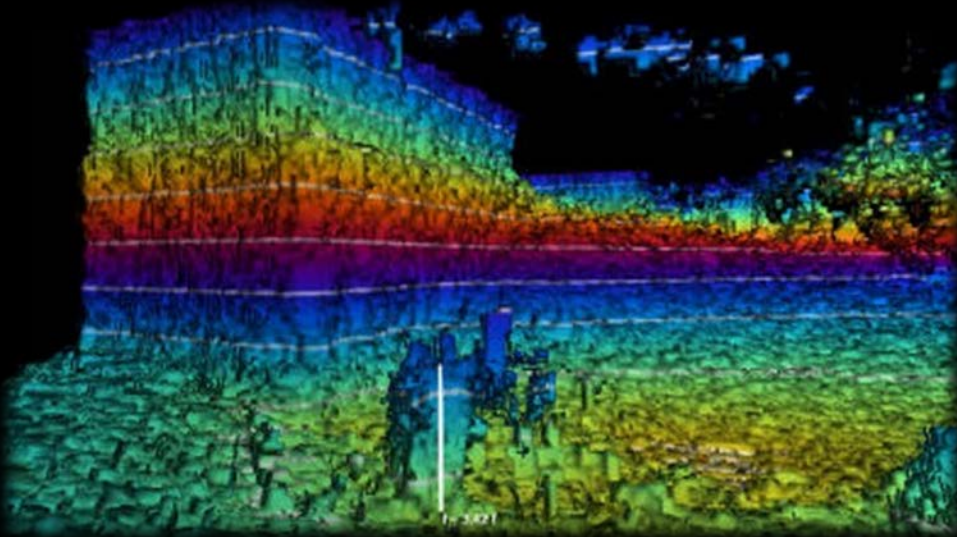


*Returns recorded from each ping to the extent of the range limit*



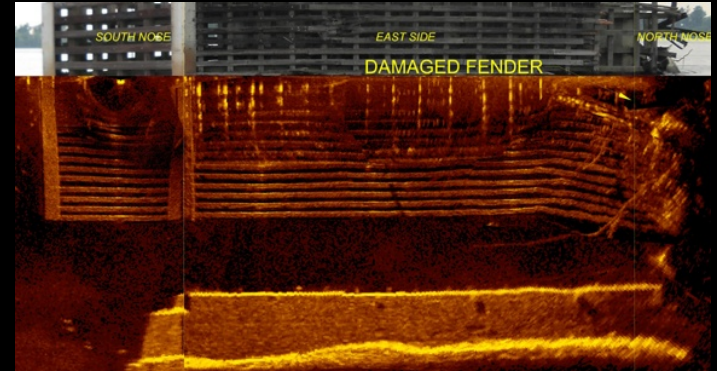
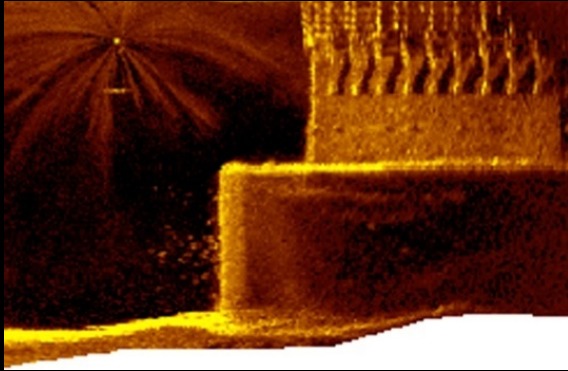
# Imagery Generated with a Coda Echoscope Multibeam System

*Courtesy of CodaOctopus*

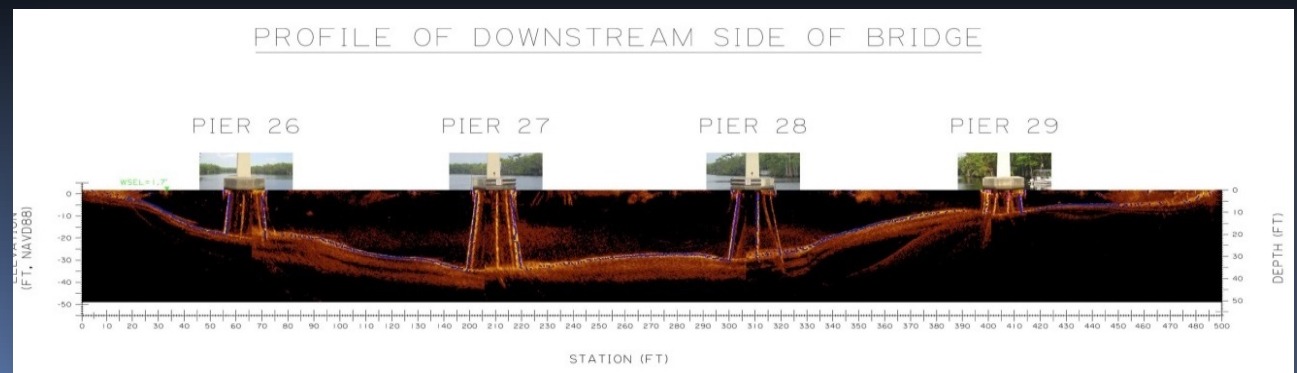
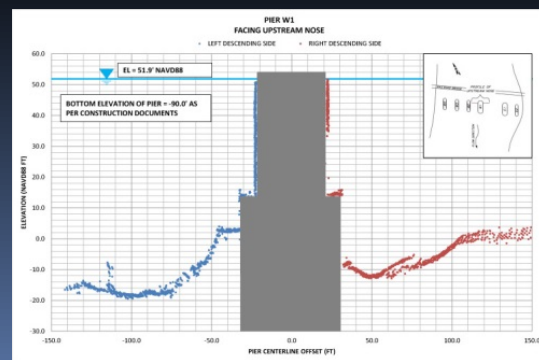


# Steered Beam Acoustic Remote Sensing Systems Utilized for Acoustic Imaging & Profiling

*Provides the best results over a wide range of conditions*

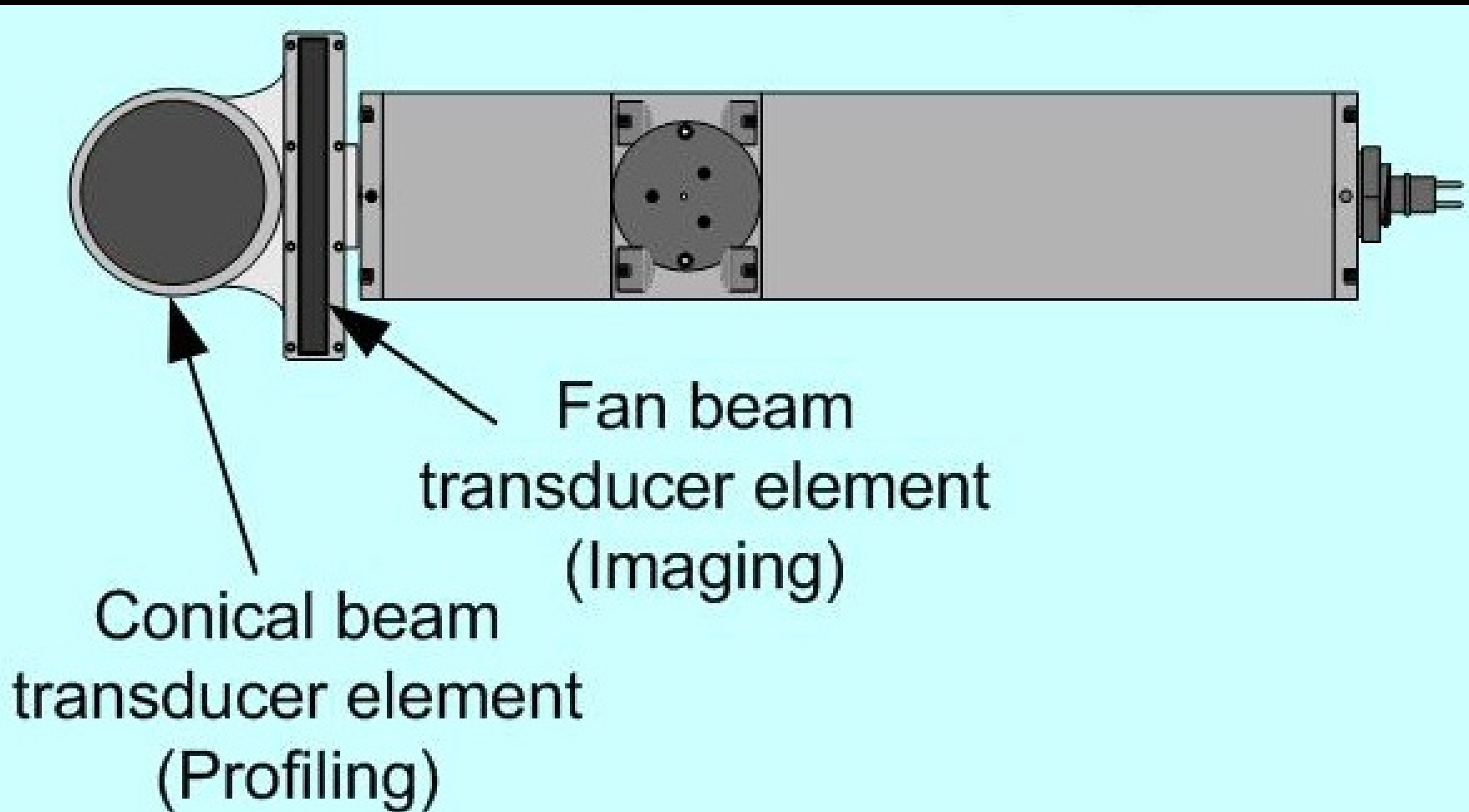


*Dual element system, optimized for high turbidity, high flow environments providing imagery visualization and profiling metrology*



# Dual Element – Multi-axis Steered Beam Remote Sensing Unit

*Based on A Kongsberg Mesotech MS1000*

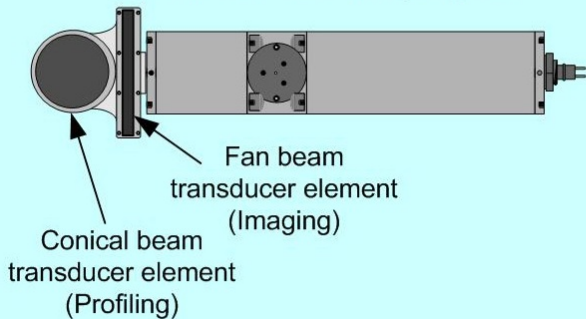




# Acoustic Profiling Patterns and Achievable Resolutions

## Acoustic profiling system footprint and methodology

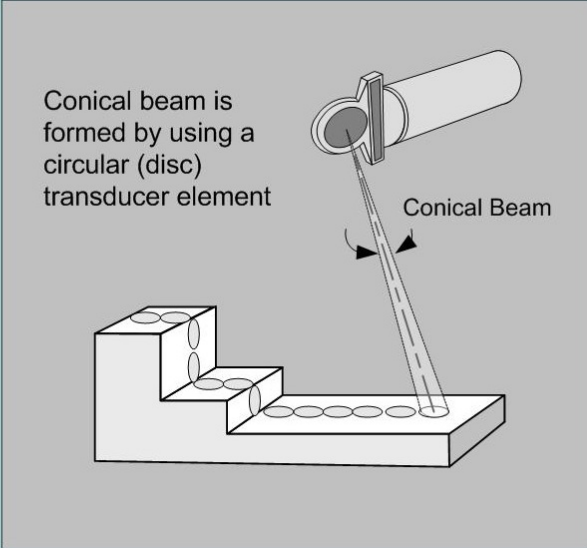
For profiling applications the head must be mounted horizontal with the 0-degree reference mark vertically aligned



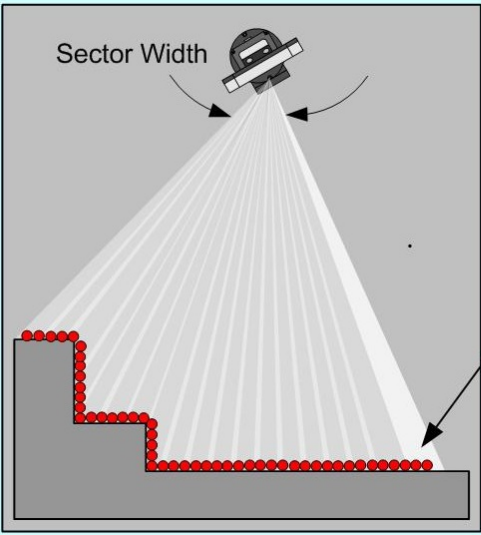
Conical beam transducer element (Profiling)

Fan beam transducer element (Imaging)

Conical beam is formed by using a circular (disc) transducer element



Conical Beam



Sector Width

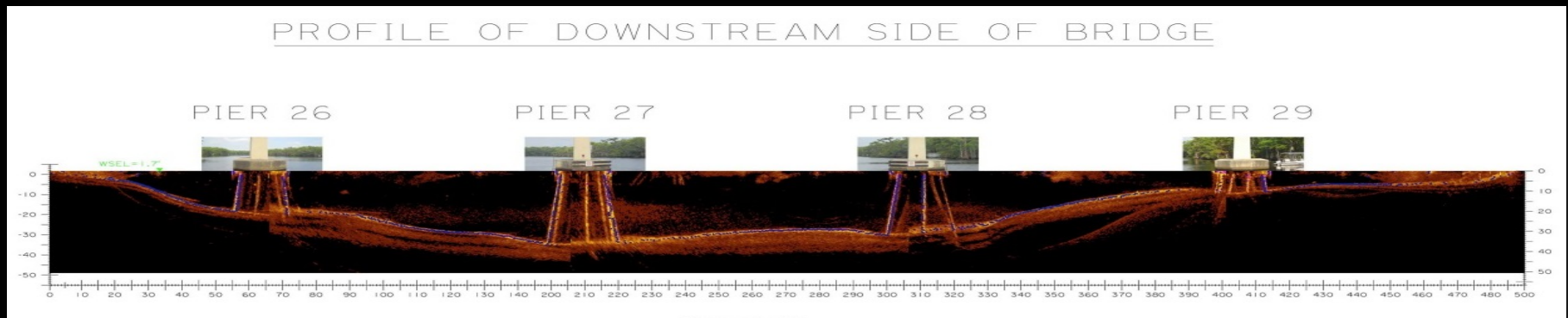
Profile points are generated by an algorithm in the MS 1000 program that detects the echoed return and assigns a range and bearing relative to the sonar transducer and its "0"-degree reference.

The number of profile points on a specific scan is set by the selected MS 1000 "Step Size" - typically this is every 0.45 or 0.9 degrees.

Sector Width and Heading are used to orient the head scan angle and arc of acoustic coverage.

The profile points can be extracted and recorded in real-time or during post processing where different weighting values can be (if desired) applied to the profile point extraction algorithm.

# Typical Profiling Data Results: Comprehensive Cross Channel Representation

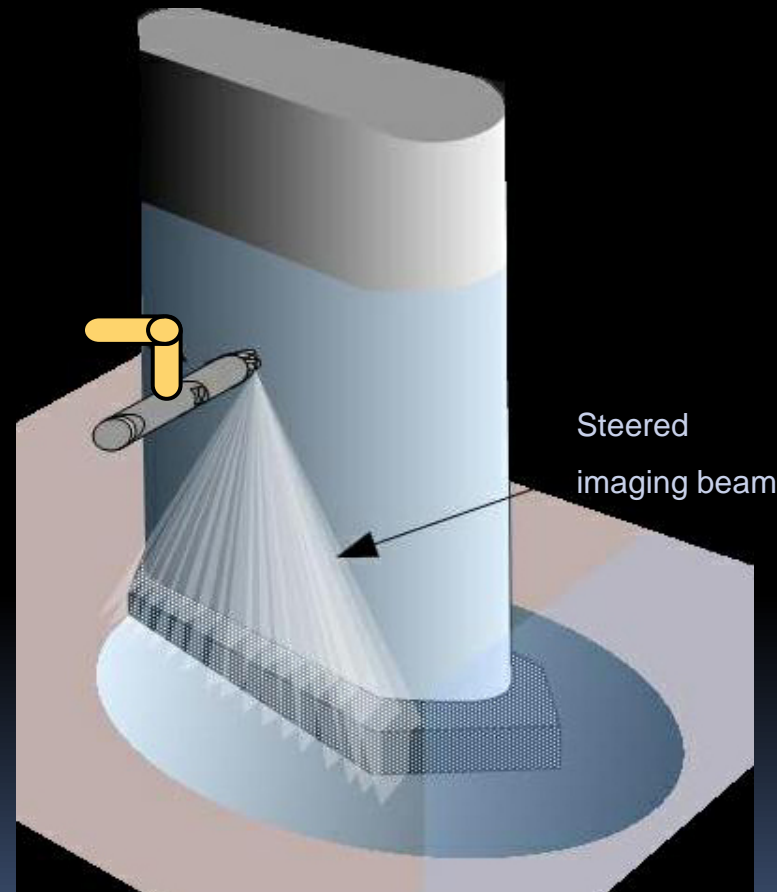
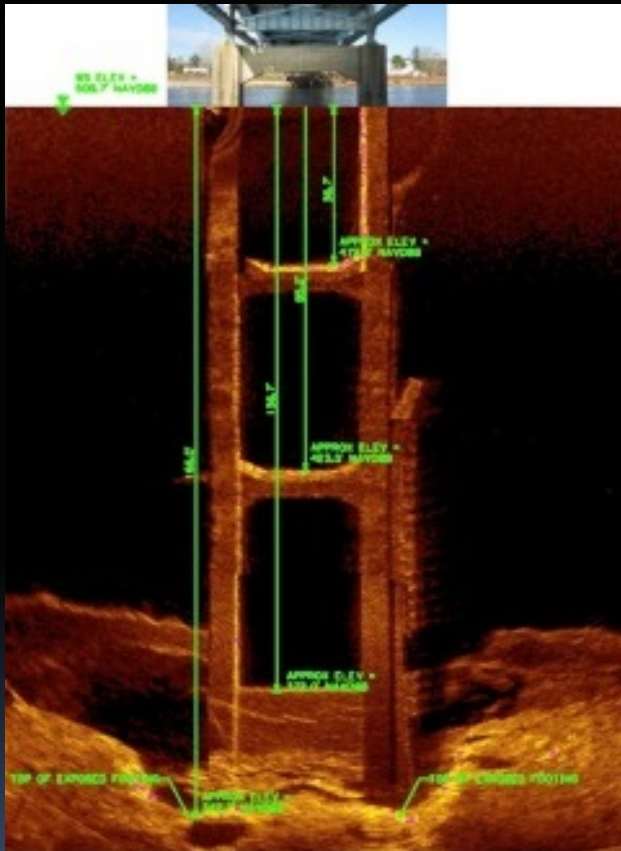


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# Steered Beam Sonar

*Integration of multi-axis steered platform, position and tracking Instrumentation is key to providing optimal visualization results*



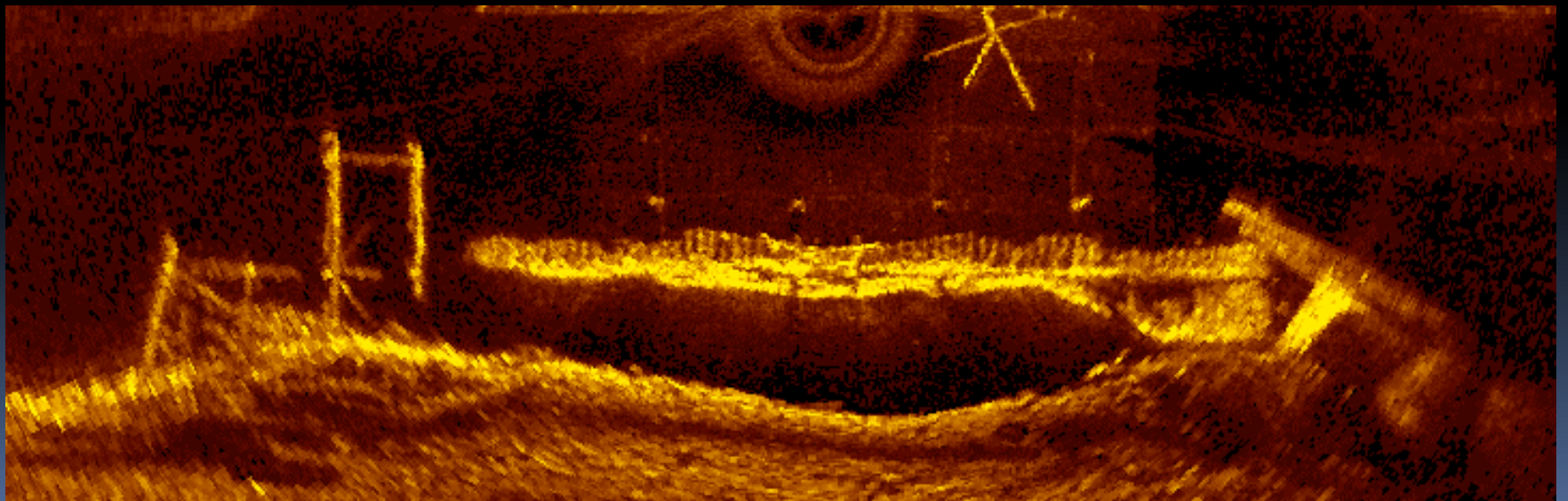
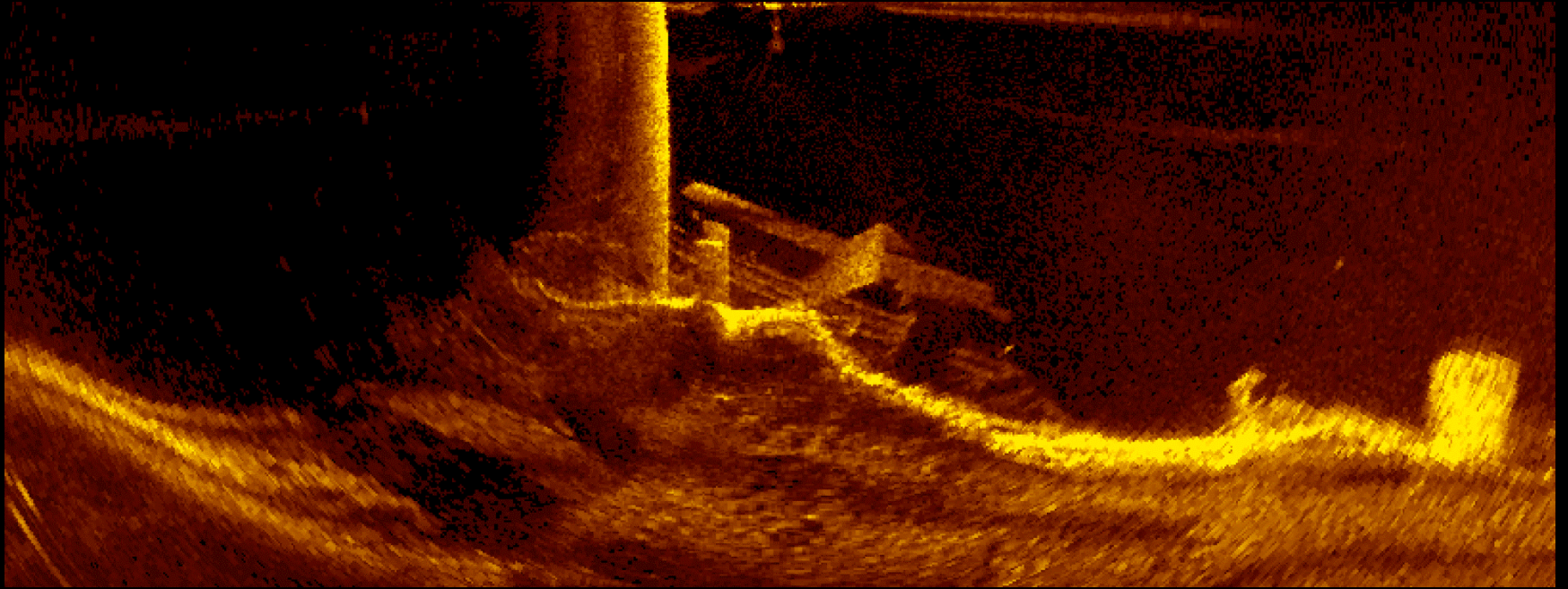
*Visualization is accomplished by utilizing steered, fan acoustic beam, which is multi-axis steerable*



# Evaluation Procedures for Underwater Acoustic Imaging and Diving

- **Step 1** - Perform the UAI inspections on bridges
- **Step 2** - Construct sonar visualization mosaics and water bottom profiles
- **Step 3** - Review results of UAI and identify “anomalies” warranting further investigation
- **Step 4** - Perform follow-up diving investigations
- **Step 5** - Generate final report comprised of all data and results

# Example Sites





# Customized Sensor Deployment Configurations



*Deep, high water current -  
deployment and  
maneuvering system*



*Boat deployment*

*Mobile deployment and maneuvering  
system*

*Tripod mounting for  
stationary, free standing  
deployment*





# Mississippi River



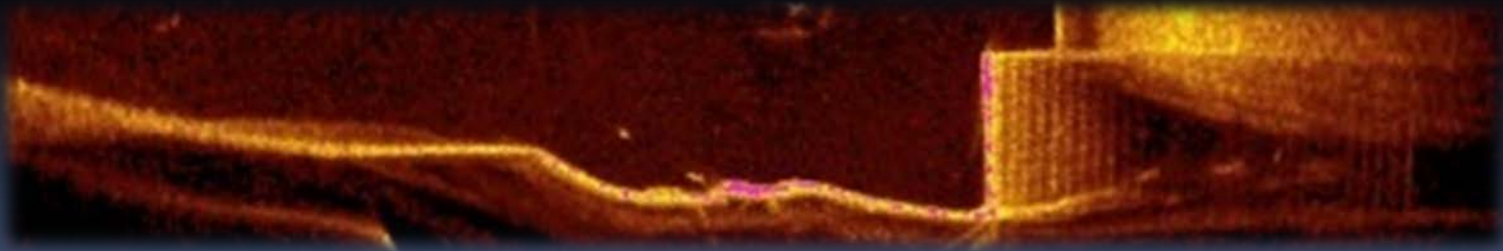
*Scour and debris evident*



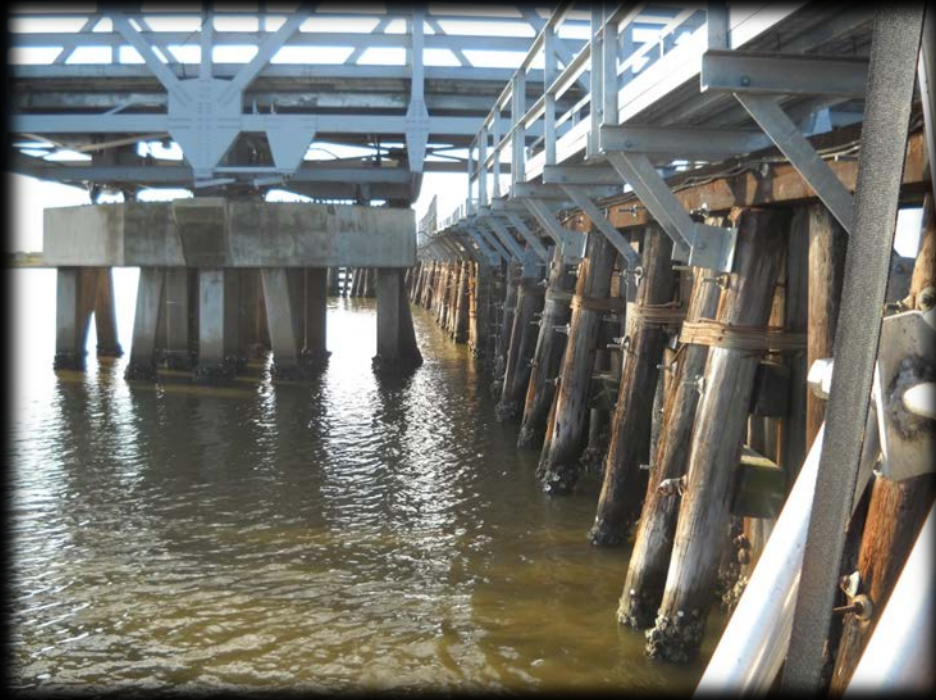
# Red River



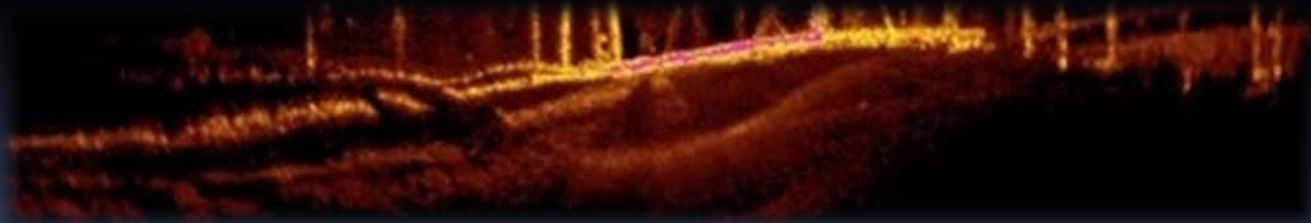
*Localized scour and exposed sheet pile encasement shown*



# Mermentau River



*High density of closely spaced piles and close proximity of fender system produces difficulties for UAI effectiveness*

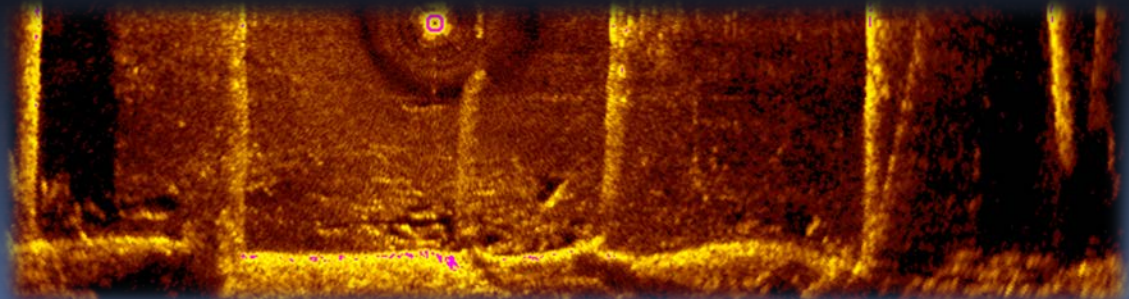




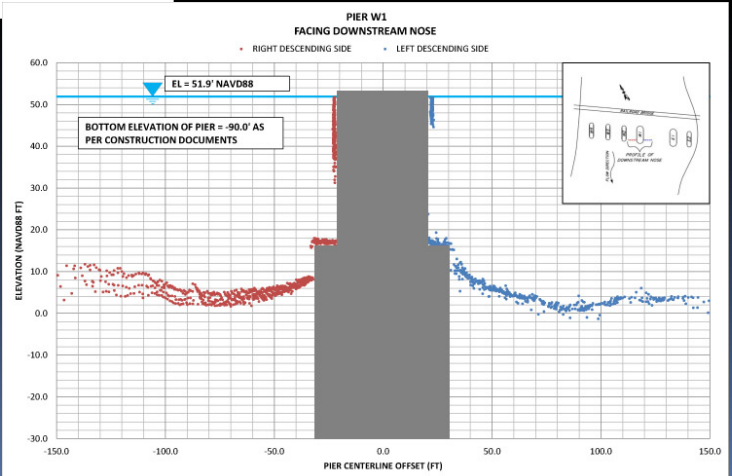
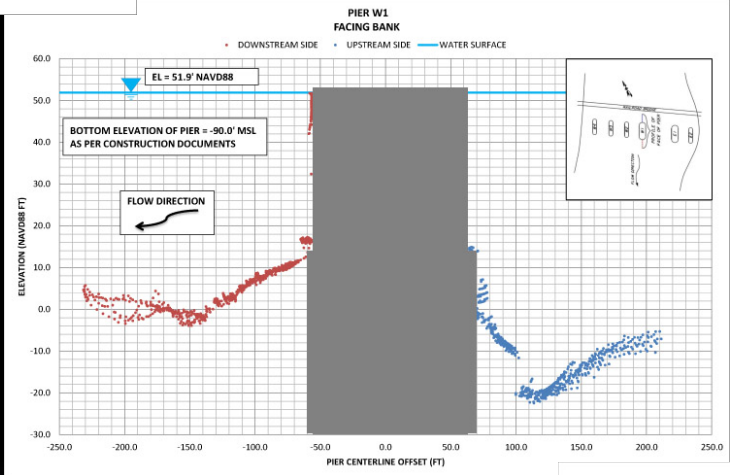
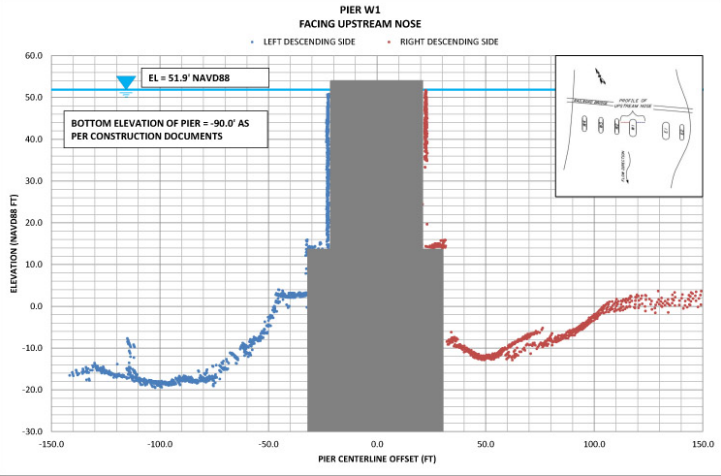
# The Bayou Teche



*Very shallow and  
minor waterway;  
however, documents  
voids*



# Localized scour profile mapping



# Analysis Review





# Diving Inspections

- *Inspected “anomalies”*
- *Verification of procedure*



# Results and Lessons Learned

- *Successfully scanned all bridges*
- *Dove on portions of all bridges*
- *Verified scanning with diving*
- *Documented scour*
- *Provided comprehensive reports on all bridges*

# Results and Lessons Learned

## *UAI worked well and very useful for:*

- *Bridges with massive piers*
- *High flow combined with significant depth*
- *No visibility with significant debris*
- *Significant scour and need to document*
- *Significant, close proximity commercial vessel traffic combined with any of the above*





# Results and Lessons Learned



## UAI did not work well for:

- *Waterline or above waterline footings with piles or drilled shafts below*
- *Shallow conditions <15' especially without propensity for scour*

# Benefits Provided by Underwater Acoustic Imaging

- *Comprehensive overall perspective*
- *Implementation in all environment conditions*
- *Visualization and metrology of localized scour conditions*
- *Added element of safety*



# Questions?

